

MikroKontroler

Eri Prasetyo Wibowo
Universitas Gunadarma

Why do we need to learn Microprocessors/controllers?

- The microprocessor is the core of computer systems.
- Nowadays many communication, digital entertainment, portable devices, are controlled by them.
- A designer should know what types of components he needs, ways to reduce production costs and product reliable.

Different aspects of a microprocessor/controller

- Hardware :Interface to the real world
- Software :order how to deal with inputs

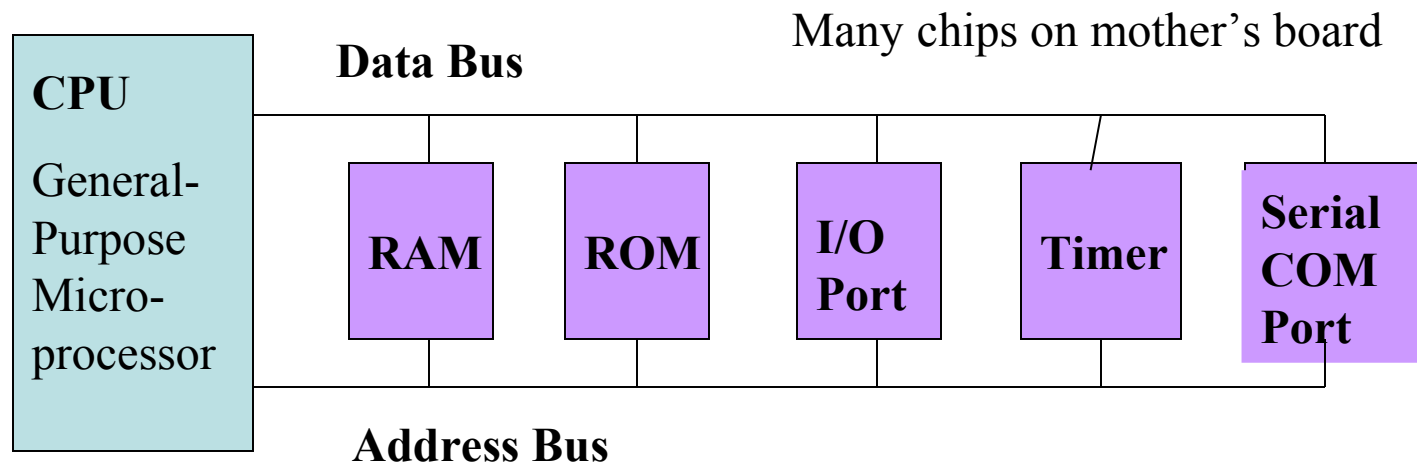
The necessary tools for a microprocessor/controller

- CPU: Central Processing Unit
- I/O: Input /Output
- Bus: Address bus & Data bus
- Memory: RAM & ROM
- Timer
- Interrupt
- Serial Port
- Parallel Port

Microprocessors:

General-purpose microprocessor

- CPU for Computers
- No RAM, ROM, I/O on CPU chip itself
- Example : Intel's x86, Motorola's 680x0



General-Purpose Microprocessor System

Microprocessor vs. Microcontroller

Microprocessor

- CPU is stand-alone, RAM, ROM, I/O, timer are separate
- designer can decide on the amount of ROM, RAM and I/O ports.
- expansive
- versatility
- general-purpose

Microcontroller

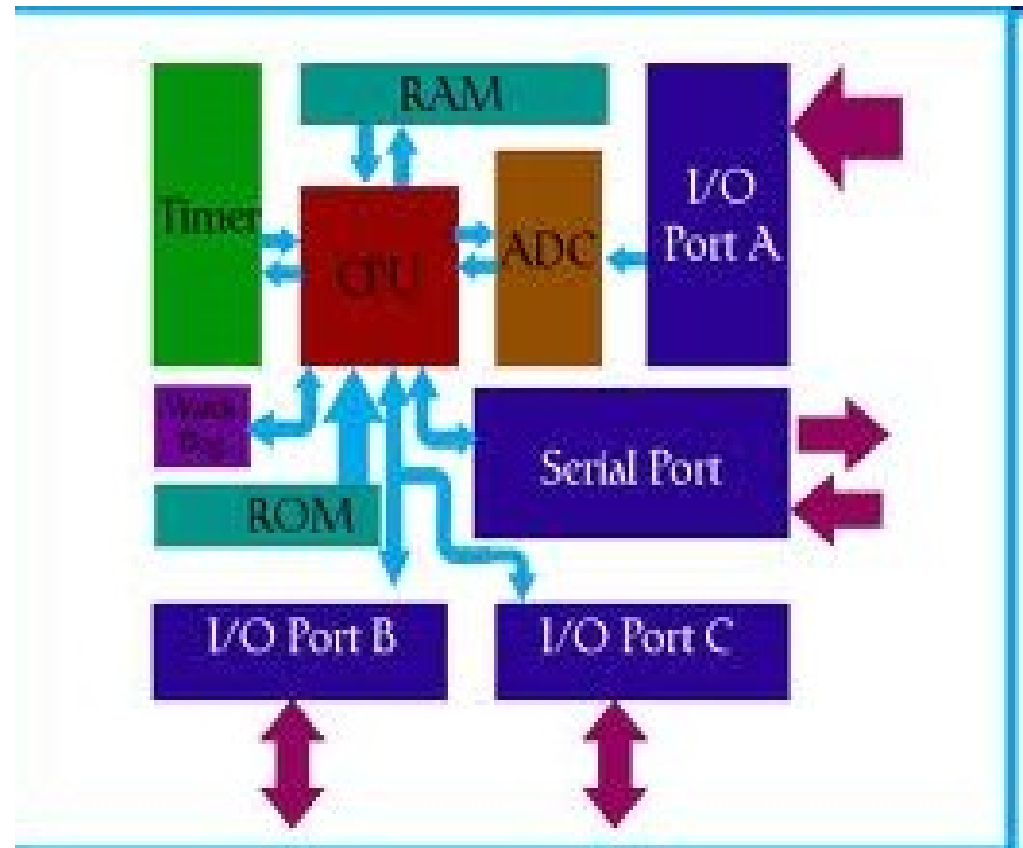
- CPU, RAM, ROM, I/O and timer are all on a single chip
- fix amount of on-chip ROM, RAM, I/O ports
- for applications in which cost, power and space are critical
- single-purpose

Three criteria in Choosing a Microcontroller

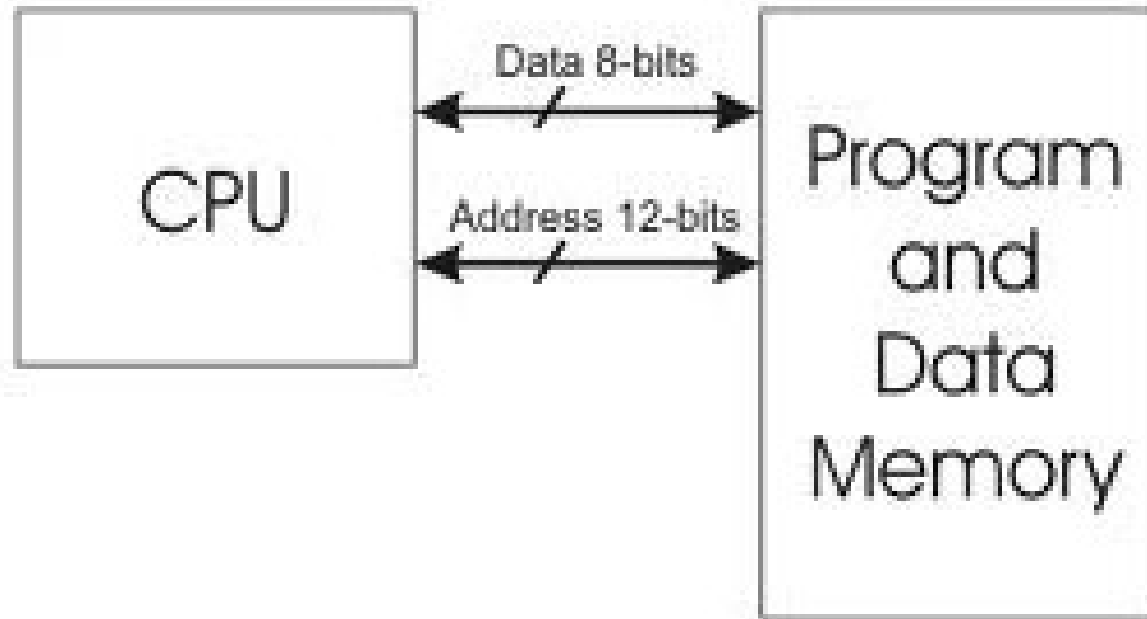
1. meeting the computing needs of the task efficiently and cost effectively
 - speed, the amount of ROM and RAM, the number of I/O ports and timers, size, packaging, power consumption
 - easy to upgrade
 - cost per unit
2. availability of software development tools
 - assemblers, debuggers, C compilers, emulator, simulator, technical support
3. wide availability and reliable sources of the microcontrollers.

Apa Mikrokontroler ?

- Small-Computer
 - Microprocessor
 - The Brains
 - Arithmetic Logic Unit (ALU)
 - Control Unit
 - Program/ Data Storage
 - Peripherals (Input/Output)
- Low-Cost

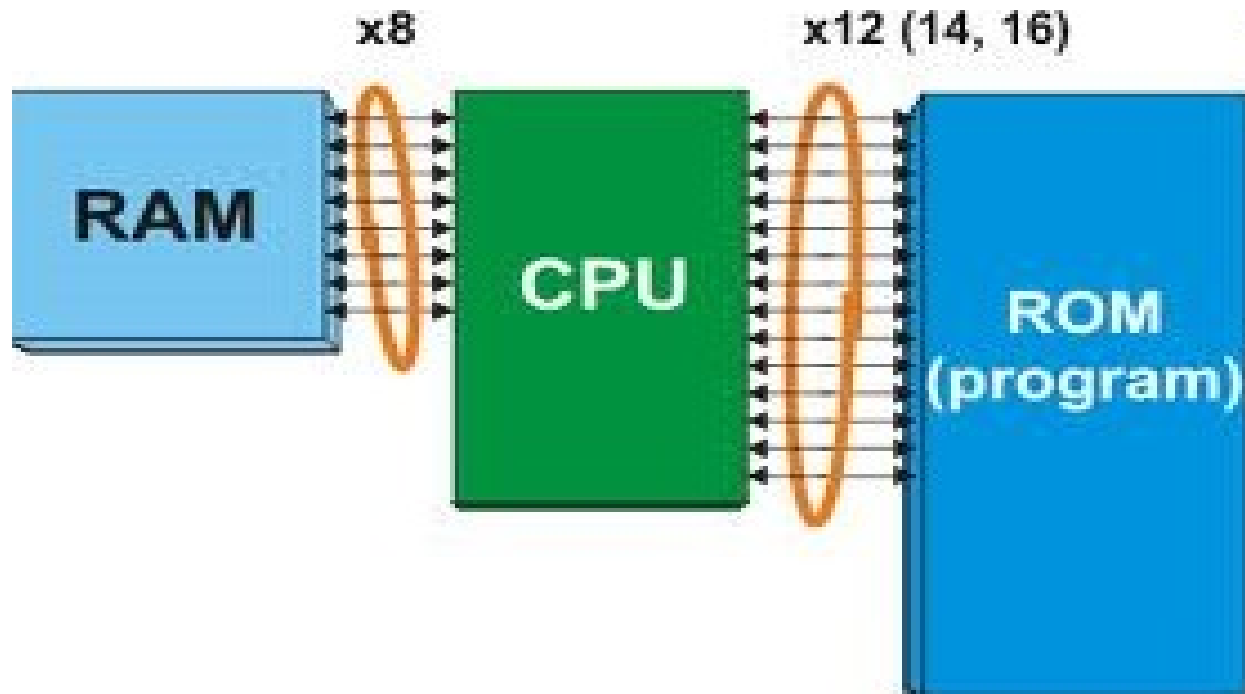


Arsitektur Von Neumann



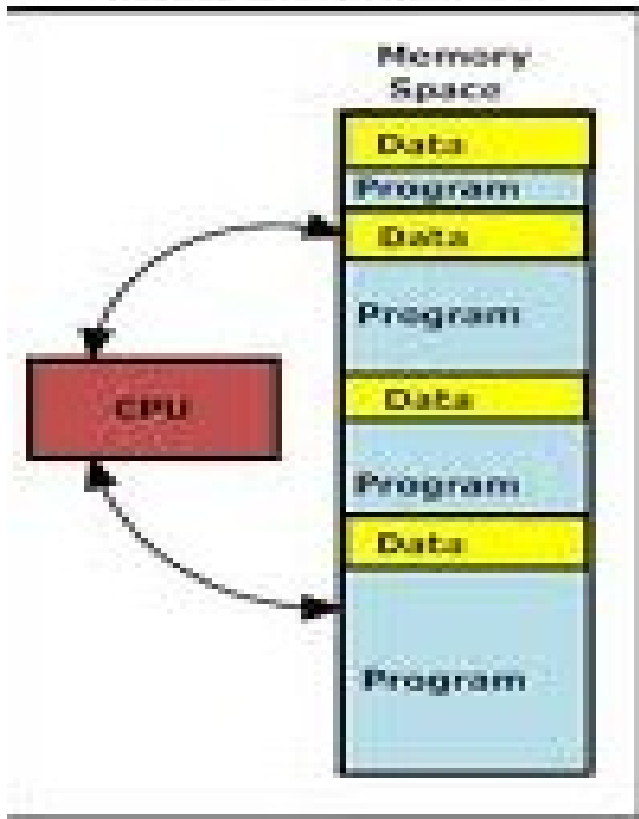
The given bus widths are examples only!

Arsitektur Harvard

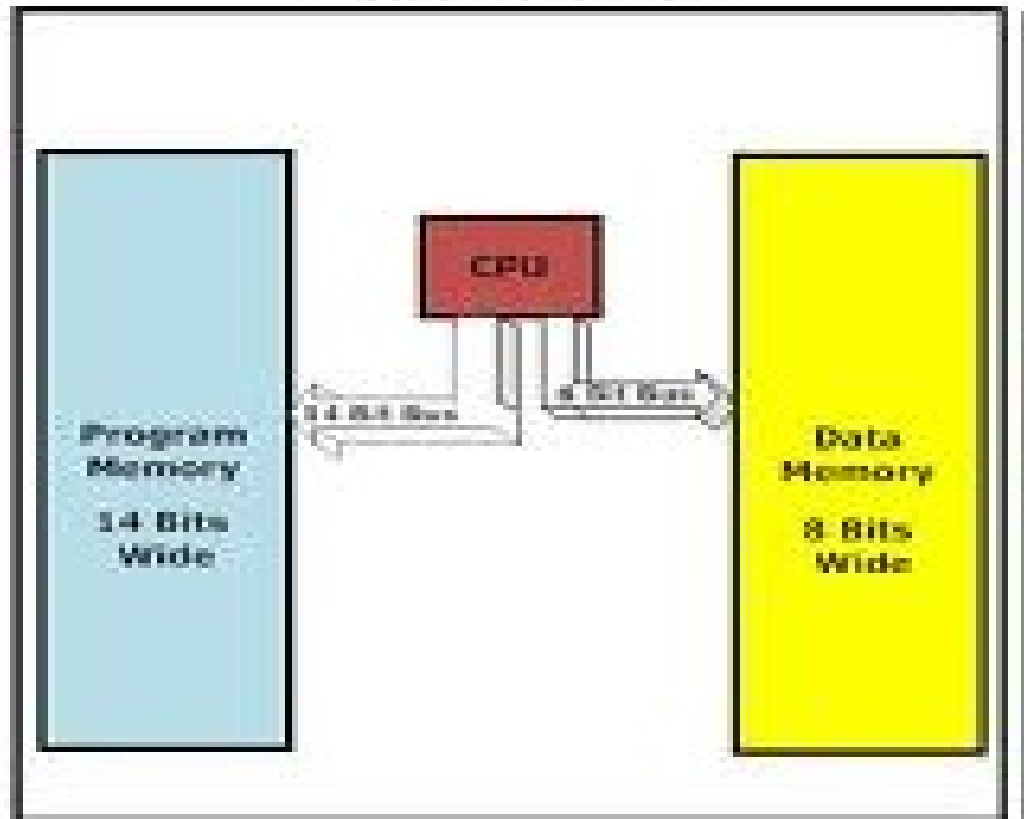


Perbedaan Keduanya

Von Neumann Architecture

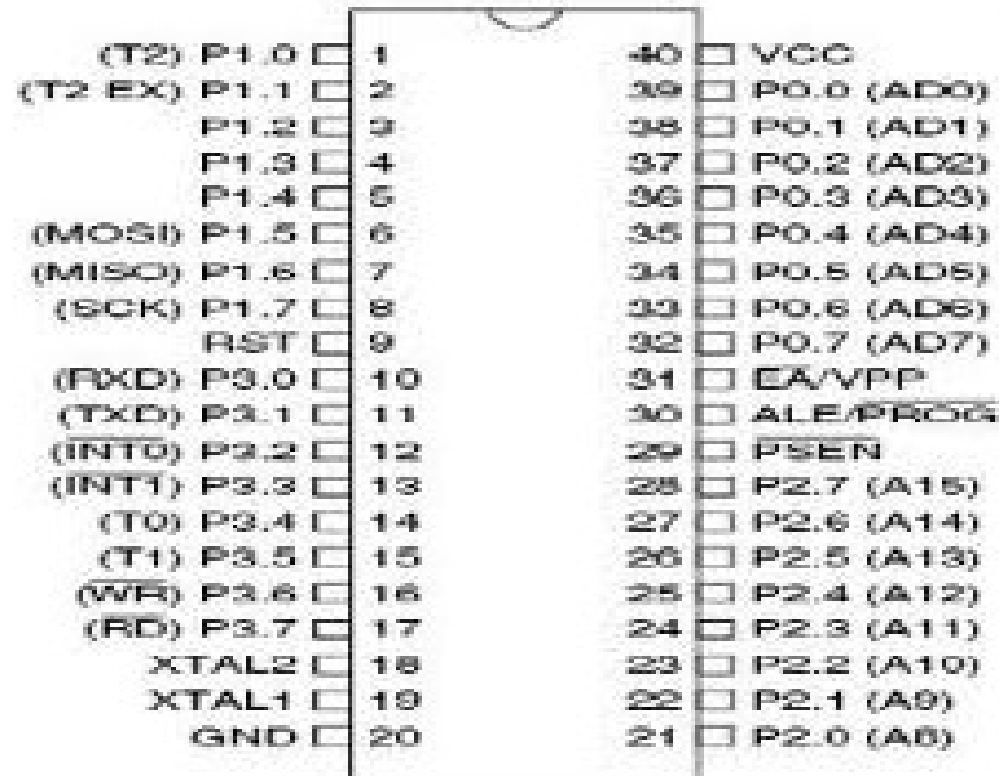


Harvard Architecture



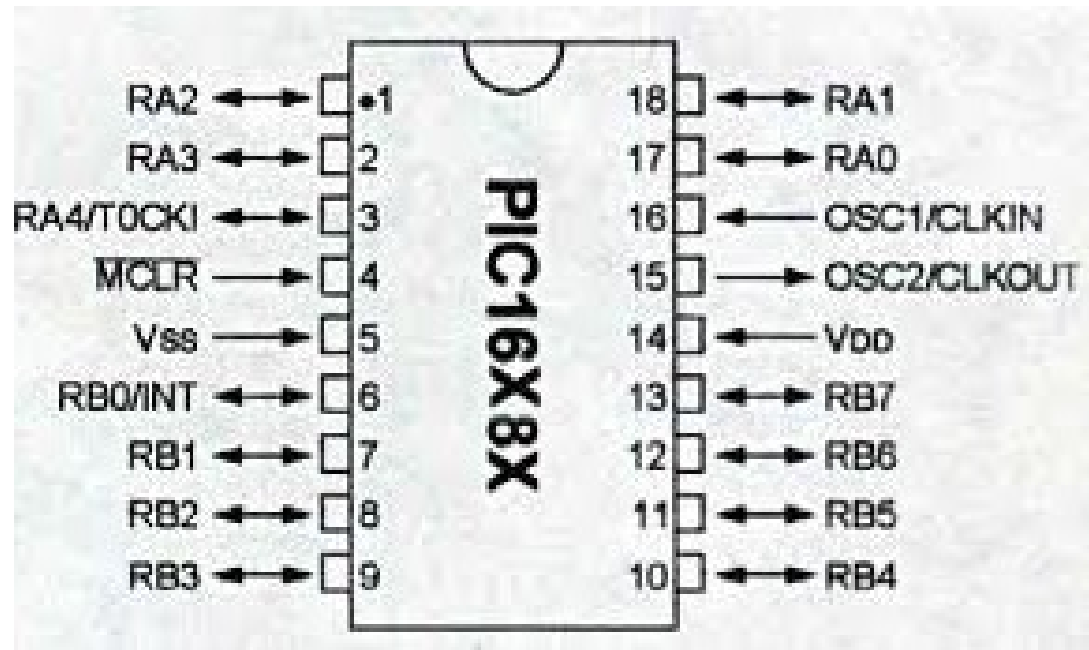
Arsitektur Mikrokontroler

- CISC, Complex Instruction Set Computing yang lebih kaya intruksi tetapi fasilitas internal secukupnya (AT89 memiliki 255 intruksi)



Arsitektur Mikrokontroler

- RISC, Reduce instruction Set Computing yang lebih kaya fasilitas internalnya tetapi jumlah intruksi secukupnya (PIC16F hanya sekitar 30 intruksi)



Perbandingan CISC dan RISC

- Pendekatan CISC

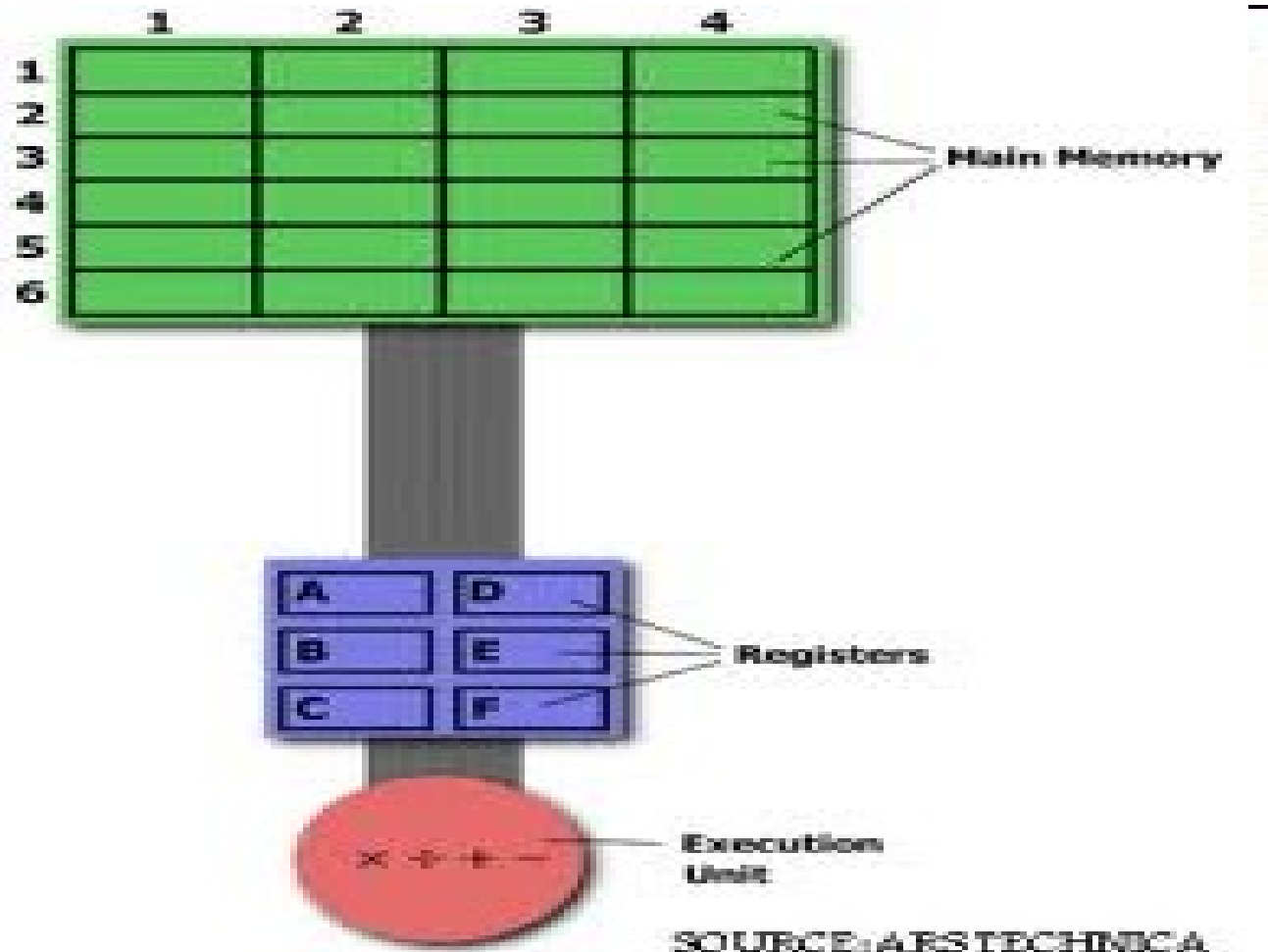
- Melaksanakan perintah cukup dengan beberapa baris bahasa mesin sesedikit mungkin
- Memori ke memori “LOAD” dan “STORE” saling kerjasama
- Ukuran kode kecil , kecepatan rendah
- Transistor digunakan untuk menyimpan intruksi-intruksi kompleks

Perbandingan CISC dan RISC

- Pendekatan RISC

- Penekanan pada perangkat lunak single clock hanya sejumlah kecil intruksi
- Register ke register “LOAD” dan “STORE” adalah intruksi-intruksi terpisah
- Ukuran kode besar , kecepatan relatif tinggi
- Transistor banyak digunakan untuk register memori

Struktur Memori



- Memori terbagi menjadi beberapa lokasi (aris,kolom) dari 1,1 sd 6:4
- UNit eksekusi melakukan operasi komputasi
- Unit eksekusi beroperasi untuk data yang sudah disimpan di register (A,B,C,D,E,F)

Contoh kasus perkalian dua bilangan dalam memori

- CISC
 - MULT 2:3, 4:2,
satu angka disimpan di 2,3 angka lain disimpan 4,2, hasil perkalian disimpan di 2,3 lagi.
 - MULT dikenal dengan complex instruction, bekerja secara langsung melalui memori dan tidak memerlukan intruksi lain seperti fungsi baca atau simpan

Contoh kasus perkalian dua bilangan dalam memori

- RISC

- LOAD A, 2:3 (memindah data ke memori)

- LOAD B, 4:2

- PROD A,B (operasi product atau kali)

- STORE 2:3, A (menyimpan data hasil ke memori)